



Solar Glare Hazard Analysis Tool (SGHAT) User's Manual v. 2.0

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1. Requirements

- Use of this software requires the latest version of one of the following free web browsers: Mozilla Firefox or Google Chrome.
- The Solar Glare Hazard Analysis Tool (SGHAT) can be accessed by registering at www.sandia.gov/glare.

2. Introduction

With growing numbers of solar energy installations throughout the United States, glare from photovoltaic (PV) arrays and concentrating solar systems has received increased attention as a real hazard for pilots, air-traffic control personnel, motorists, and others. Sandia has developed a web-based interactive tool that provides a quantified assessment of (1) when and where glare will occur throughout the year for a prescribed solar installation, and (2) potential effects on the human eye at locations where glare occurs.

The Solar Glare Hazard Analysis Tool (SGHAT) employs an interactive Google map where the user can quickly locate a site, draw an outline of the proposed PV array, and specify observer locations or paths. Latitude, longitude, and elevation are automatically recorded through the Google interface (see Figure 1), providing necessary information for sun position and vector calculations. Additional information regarding the orientation and tilt of the PV panels, reflectance, environment, and ocular factors are entered by the user.

If glare is found, the tool calculates the retinal irradiance and subtended angle (size/distance) of the glare source to predict potential ocular hazards ranging from temporary after-image to retinal burn. The results are presented in a simple, easy-to-interpret plot that specifies when glare will occur throughout the year, with color codes indicating the potential ocular hazard. The tool can also predict relative energy production while evaluating alternative designs, layouts, and locations to identify configurations that maximize energy production while mitigating the impacts of glare.





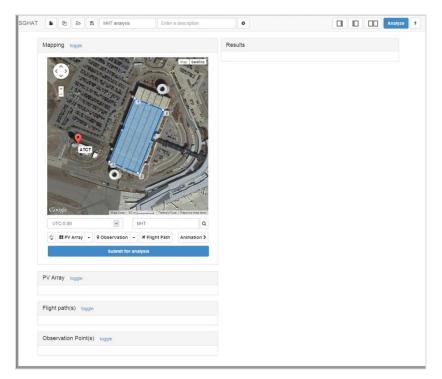


Figure 1. Screen image of SGHAT page with Google Map interface.

3. Changes from Version 1

SGHAT version 2 includes several significant updates from Version 1. These changes are summarized below. Detailed explanations of each update can be found in later sections.

- **Flight Path Tool**. Flight paths can now be drawn on the map using the flight path tool. A flight path consists of nine observation points: a threshold point, which should be located at the runway threshold, and eight observation points extending from the threshold at quarter-mile intervals. The threshold crossing height and flight path direction can be modified by the user.
- **Updated User Interface**. The UI has been overhauled to provide for more streamlined usage. No more tabbing between results and map each section is now shown side-by-side and can be expanded or collapsed depending on the focus.
- **Analysis Persistence**. Analysis parameters and components are now saved automatically. Analyses can be closed and re-loaded without loss of information.
- Manual Entry of Coordinates. The user can now manually adjust the latitude and longitude coordinates of the PV array vertices or observation points (except flight paths).





4. Assumptions and Limitations

Below is a list of assumptions and limitations of the models and methods used in SGHAT:

- The software currently only applies to flat reflective surfaces. For curved surfaces (e.g., focused mirrors such as parabolic troughs or dishes used in concentrating solar power systems), methods and models derived by Ho et al. (2011) [1] can be used and are currently being evaluated for implementation into future versions SGHAT.
- SGHAT does not currently apply to tracking systems. The majority of PV installations are currently fixed tilt (do not track), but we are planning on implementing single-axis tracking to the tool in the future. Two-axis tracking, when operating properly, will not yield significant stray light reflections since the module will be pointing toward the sun.
- SGHAT does not rigorously represent the detailed geometry of a system; detailed
 features such as gaps between modules, variable height of the PV array, and support
 structures may impact actual glare results. However, we have validated our models
 against several systems, including a PV array causing glare to the air-traffic control tower
 at Manchester-Boston Regional Airport and several sites in Albuquerque, and the tool
 accurately predicted the occurrence and intensity of glare at different times and days of
 the year.
- SGHAT assumes that the PV array is aligned with a plane defined by the total heights of the coordinates outlined in the Google map. For more accuracy, the user should perform runs using minimum and maximum values for the vertex heights to bound the height of the plane containing the solar array. Doing so will expand the range of observed solar glare when compared to results using a single height value.
- SGHAT does not consider obstacles (either man-made or natural) between the observation points and the prescribed solar installation that may obstruct observed glare, such as trees, hills, buildings, etc.
- The tool currently uses a constant reflectance for the solar modules as prescribed by the user. In actuality, the reflectance increases with increasing incidence angle. We are currently collecting data on the solar reflectance as a function of incidence angle for different modules and glass types. We plan on implementing this new feature in a future version so that the user can choose a module and/or glass type to specify a more accurate representation of the solar reflectance as a function of incidence angle.
- The variable direct normal irradiance (DNI) feature (if selected) scales the user-prescribed peak DNI using a typical clear-day irradiance profile. This profile has a lower DNI in the mornings and evenings and a maximum at solar noon. The scaling uses a clear-day irradiance profile based on a normalized time relative to sunrise, solar noon, and sunset, which are prescribed by a sun-position algorithm [2] and the latitude and longitude obtained from Google maps. The actual DNI on any given day can be affected by cloud cover, atmospheric attenuation, and other environmental factors.
- The ocular hazard predicted by the tool depends on a number of environmental, optical, and human factors, which can be uncertain. We provide input fields and typical ranges of values for these factors so that the user can vary these parameters to see if they have an





impact on the results. The speed of SGHAT allows expedited sensitivity and parametric analyses.

5. User Interface

The SGHAT user interface has been rebuilt to accommodate the 2.0 features. The four primary UI sections are labeled below.

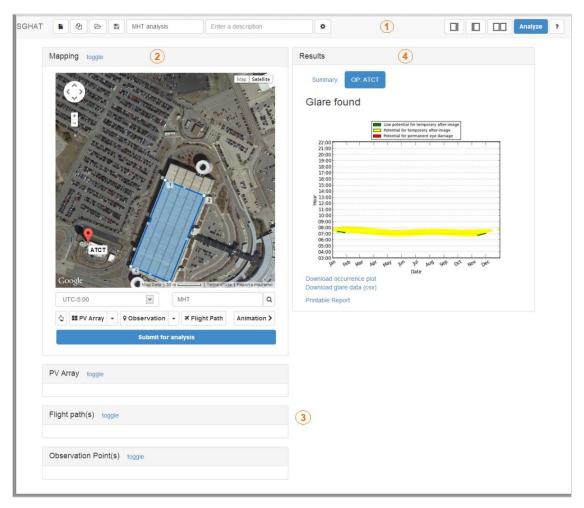


Figure 2. Updated SGHAT user interface with labeled sections: 1) analysis menu bar, 2) mapping interface, 3) component data sections, 4) results section.

5.1 Analysis Menu Bar

The menu bar contains buttons for working with analyses and expanding/collapsing various sections. The left portion of the menu bar deals with analyses and their parameters:





Figure 3. Left side of analysis menu bar.

1. New Analysis

Brings up the New Analysis screen where the user can enter a name and select a timezone to create a new analysis. The previous analysis will be saved.

2. Clone Analysis

Create a new analysis and populate it with the components (PV array, observation points, flight paths) of the current analysis. This is similar to the common "Save As..." functionality.

3. Load Analysis

Display a list of previously-saved analyses. Select an analysis to load it, or click "delete" to permanently delete it.

4. Save

Save the current analysis and components. Note that analyses and components are auto-saved when changed.

5. Analysis name

Modify the name of the current analysis. The name must be unique.

6. Analysis description

An optional description can be entered. The description does not have to be unique.

7. Analysis configuration

Display the analysis configuration screen. Use this to change parameters such as the time interval, height units, etc. See Appendix A for detailed descriptions of each parameter.

The right portion of the menu bar has the following buttons:



Figure 4. Right side of analysis menu bar.

1. Expand Map and Component sections

Expand the left sections (mapping and components). The Results section on the right is minimized.





2. Expand Results section

Expand the Results section to fill the screen. The mapping and component sections are minimized.

3. Restore Both

All sections are restored to their original sizes and take up 50% of the screen.

4. Analyze

Submit the current analysis for processing. A glare analysis will be performed based on the analysis parameters and drawn components (PV array, observation point(s) and/or flight path(s)).

5. View Help

Display the Help screen which provides a quick-start guide and links to relevant resources.

5.2 Google Map Section and Controls

The mapping sections contains buttons for adding map components, running glare animations and setting the analysis time zone. In brief, components are added by clicking on the respective button and then clicking on the map to set the location of the component.

Observation points and the PV array can be removed by right-clicking them on the map when in Select mode, or by clicking the "Remove" button in their data section. Flight paths can be removed by clicking the "Remove" button or by clicking on the threshold point and selecting "Remove".

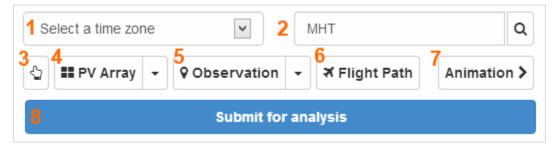


Figure 5. Map and drawing controls for adding analysis components.

1. Select time zone

Select the standard time zone offset of the location being analyzed. Options are UTC-12 through UTC+14.

2. Map search

Enter a location to center the Google Map. This functions exactly like the actual Google Map search. Note that analysis components are not affected when the map location changes.





3. Select Tool

Activate the Map Select Mode to manually pan the map or move the position of PV array vertices and observation points. Note that flight path observation points can only be adjusted by changing the flight path direction.

4. PV Array Tool

Activate the PV array drawing mode to draw an array on the map. The default mode uses click-and-drag to draw a rectangular PV array. Use the drop-down menu to select Polygonal mode in order to click and set each array vertex manually.

5. Observation Point Tool

Activate the Observation Point drawing mode. Click on the map to add a new observation point. SGHAT automatically queries Google for the ground elevation of the point. Using the dropdown menu, select the ATCT Point mode to automatically set the observation point label to 'ATCT'.

6. Flight Path Tool

Activate the flight path drawing mode. Click once on the map to set the runway threshold point. Click again to specify the flight path direction. Eight observation points will be added in this direction, spaced at quarter-mile intervals on the map.

7. Animation Menu

Click to open the Animation Menu:

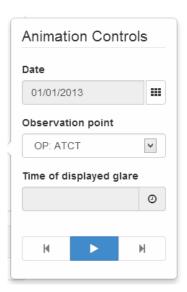


Figure 6. Animation controls.

In the menu, select a date and observation point and click the Play button to view the location of glare along the PV array surface for the given day, as it changes over time. The Backwards and Forwards buttons can be used to manually step through the times of glare.





8. Submit Analysis

Submit the analysis parameters and components for glare analysis. The results will appear in the Results section once the analysis is complete.

5.3 Component Data Sections

There are three component types: PV array, flight path and observation point. When drawn on the map, the properties of each component are displayed in a respective component section for convenient editing.

PV Array Section

The PV array sections displays the configurable parameters of the PV array and its vertices (corners).

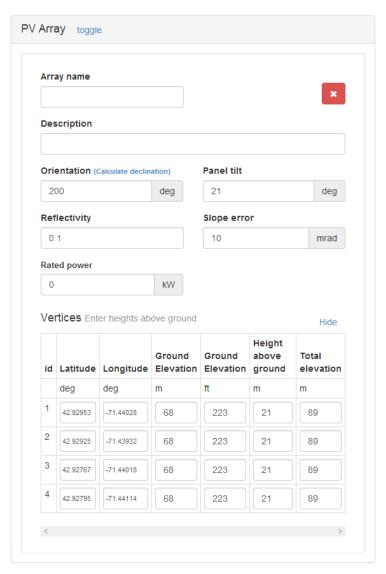


Figure 7. Sample data section of PV array, including table of vertex (corner) coordinates.





See Appendix B for detailed descriptions of each parameter.

Note that the array vertex parameters are all editable – entering a new latitude or longitude will automatically adjust the corresponding vertex on the map. Values for vertex heights above ground must be entered before a glare analysis can be performed.

Flight Path Section

The flight path section contains entries for each flight path added on the map. Each entry displays the configurable parameters of the flight path as well as non-editable observation points.

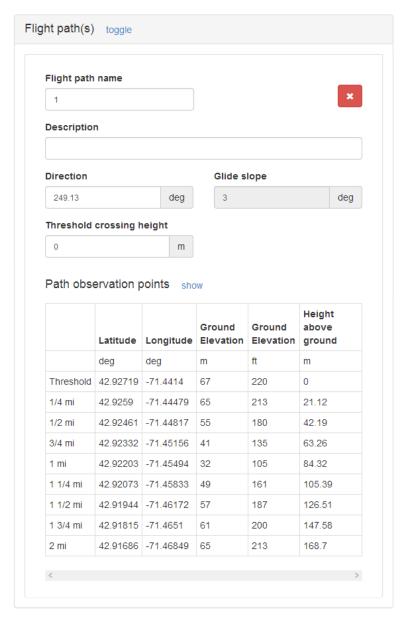


Figure 8. Sample data section of flight path, including table of observation point coordinates.





Note that the glide slope is set to 3 degrees and observation point parameters cannot be altered – this is to conform to the Federal Aviation Administration guidelines for analyzing flight paths.

Observation Point Section

Non-flight-path observation points are displayed in a tabular format in their data section:



Figure 9. Observation point data section with two sample observation points.

Observation points are fully editable. Changes to the name, latitude or longitude of an observation point will be reflected on the map.

5.4 Results Section

Glare analysis results are displayed in the Results section on the right side of the SGHAT page.

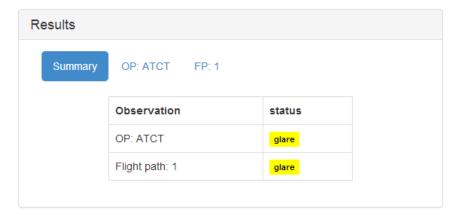


Figure 10. Results section summary tab, with overview table of glare found.





A table summarizes the resulting glare for each flight path and observation point. Links on the top of the results section can be used to navigate to specific results.

Observation Point Results

Observation points that experience glare will show results similar to the following figure:

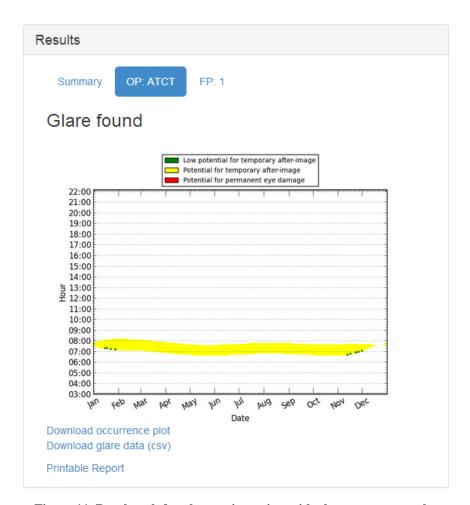


Figure 11. Results tab for observation point, with glare occurrence plot.

The Observation Point ("OP") result shows the glare occurrence plot and links for the plot and for downloading the glare data in comma-separated format. Finally, a Printable Report can be accessed which allows for printing the results in a summary fashion.

Flight Path Results

Flight path results contain data for any glare found at each observation point. A tabular summary of glare results appears at the top of the section, similar to the Results Summary table. A link to a printable Full Report can be used to print a summary of the entire flight path analysis. Below the table, results for each observation point are provided.



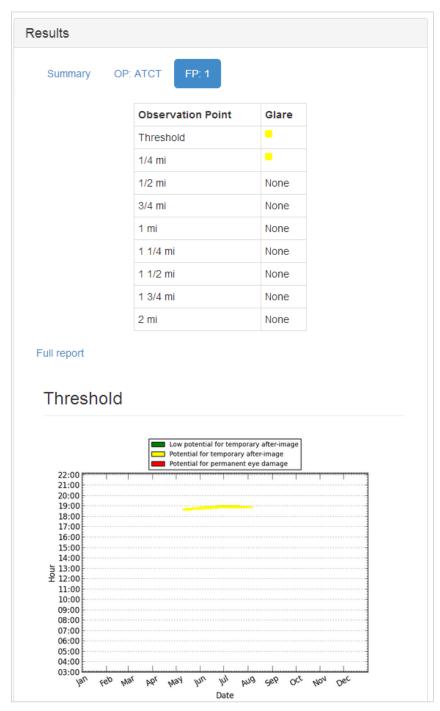


Figure 12. Results tab for flight path, with summary table of glare found and results for threshold point. (Results for remaining observation points not shown in image).





Sample Glare Occurrence Plot

The Glare Occurrence Plot shows when glare can occur (as viewed from the prescribed observation point) throughout the year. The color of the dots indicates the potential ocular hazard [1] as shown in Figure 13. In the example shown in Figure 13, glare is predicted to be visible from the prescribed observation point during the morning from January to November for ~30 – 40 minutes. The color of the plotted points indicates the potential ocular hazard. In Figure 13, the yellow dots indicate that the glare in this particular example has the potential to cause a temporary after-image.

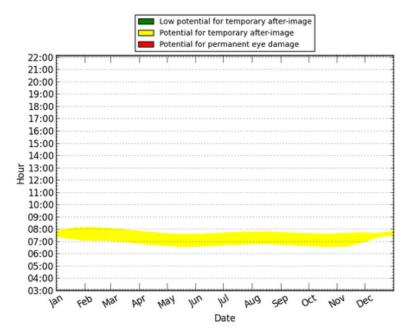


Figure 13. Glare occurrence plot showing when glare can occur (time and date) and the potential for ocular impact (represented by the color of the dots). Times are shown in Standard Time (during Daylight Savings Time, add one hour).





6. Case Study and Example

We include a sample analysis of the Manchester-Boston Regional Airport (MHT), which has experienced glare from PV panels that were installed on the roof of a parking garage near the air traffic control tower. The blue highlighted area in Figure 14 is drawn by the user to denote the location of the PV array. The red marker indicates the location of the observer in the air traffic control tower.

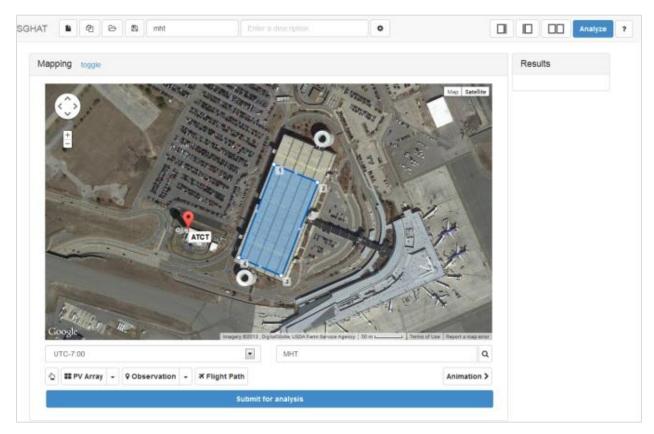


Figure 14. Screen image of glare analysis of the Manchester Boston Regional Airport. PV array (blue outline) and observation point (red marker) are entered using drawing tools integrated with Google Maps.

6.1 ATCT analysis

Figure 15 through Figure 17 show other input parameters entered by the user, including orientation and tilt of the PV array, elevations, rated power (for energy production calculations), optical and ocular parameters. The latitude, longitude, and elevation coordinates of the user-drawn PV array and observation points are automatically calculated in Google Maps and used to determine sun position and vector calculations for the glare and energy production analyses.





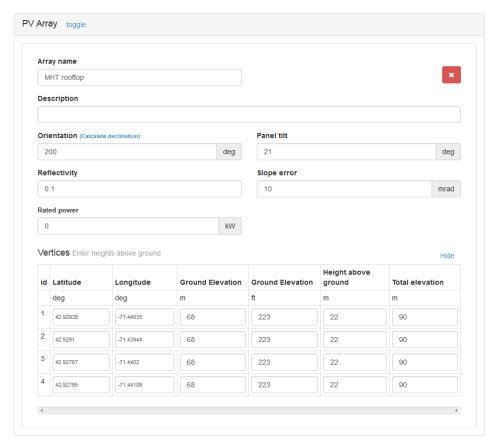


Figure 15. PV array input parameters used in SGHAT for glare analysis at MHT.



Figure 16. ATCT observation point input parameters.





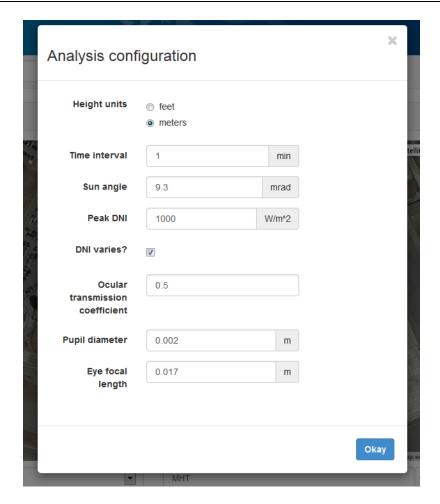


Figure 17. Analysis configuration parameters for MHT analysis.

Figure 18 and Figure 19 show the results of the glare analysis assuming different values for the optical slope error of the PV modules, which impacts the scatter and beam spread. The dots in the plot represent occurrences of glare as viewed from the user-specified observation point relative to the specified PV array as a function of the time of day and day of the year. The color of the dots indicates the potential ocular hazard, which is impacted by the direct normal irradiance, optical parameters (reflectance, slope error/scatter), and ocular parameters (pupil diameter, transmission coefficient, ocular focal length). In Figure 18 and Figure 19, there is a potential for glare that can cause temporary after-image (a lingering image of the glare in the field of view) during the early morning for most months of the year Assuming an optical slope error of 10 mrad, which yields a total beam spread of the reflected glare image of 0.13 rad (~7 degrees), predicts that glare will be visible for more days throughout the year and for a slightly longer period each day when compared to the results using a slope error of 0 mrad, which has less scatter and beam spreading (0.0093 rad or ~0.5 degrees).

At MHT, the general spatial and temporal pattern of glare is shown in Figure 20.



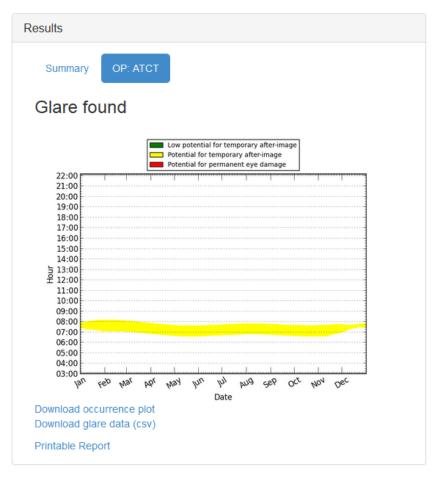


Figure 18. Results section and plot showing when glare can occur (time and date) and the potential for ocular impact (represented by the color of the dots) in the ATCT assuming an elevation of 45 m above ground level with an optical slope error of 10 mrad (total beam spread of 0.1293 rad). Times are Eastern Standard Time (during Daylight Savings Time, add one hour).





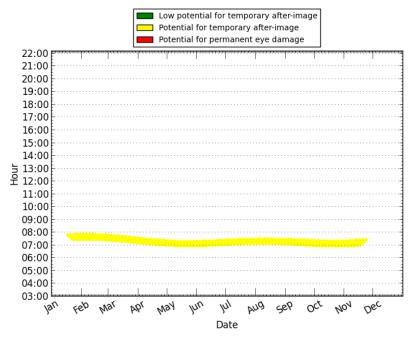


Figure 19. Glare occurrence plot for MHT ATCT with slope error of 0, yielding total beam spread of 9.3 mrad (the subtended angle of the sun).



Figure 20. Approximate predicted locations and movement of glare on PV array at various times of the year.

Photos and videos of glare from the installed PV array at MHT were taken from the Air Traffic Control Tower in late April and early May. Glare was observed during hours that were consistent with those predicted by the glare tool (see Figure 21 and Figure 22; note that the hours shown in the ocular hazard plot in Figure 18 and Figure 19 are Eastern Standard Time, but the times shown in the photos in Figure 21 and Figure 22 are Eastern Daylight Time). Because of the glare, tarp was placed over the offending PV modules.





Features such as gaps between modules, uncertainty in the relative height of the PV modules and observation points, obstructions/land features between the PV array and the observation point, uncertainty in the optical properties of the modules, and atmospheric attenuation may impact the actual perception and time of observed glare.



Figure 21. Glare viewed from Air Traffic Control Tower at Manchester/Boston Regional Airport (8:15 AM EDT, 4/27/12).





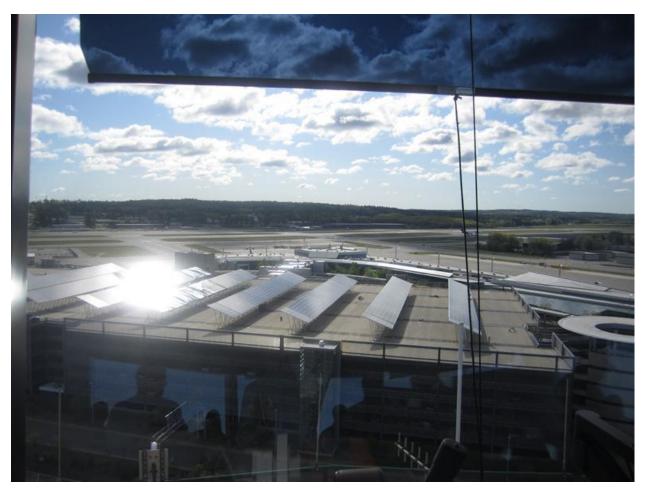


Figure 22. Glare viewed from Air Traffic Control Tower at Manchester/Boston Regional Airport (~8:17 AM EDT, 5/10/12). Note that tarp has been placed over some of the modules.

6.2 Energy optimization

The Solar Glare Hazard Analysis Tool can also be used to predict the relative energy production from alternative configurations (orientation, tilt, etc.) so that designs can be identified that not only mitigate glare but also maximize energy production. Table 1 shows alternative configurations using the same footprint of the PV array shown in Figure 14 that are predicted to produce no glare. The relative annual energy production is also shown for each configuration. In addition, the current PV configuration (200° azimuthal angle, 20.6° elevation angle) and a maximum energy production configuration (180° azimuthal angle, 43° elevation angle) are shown in Table 1. The optimal configuration using the same footprint that is predicted to produce no glare to the ATCT while maximizing energy production employs an azimuthal angle of 120° and an elevation angle of 40°.





Table 1. Alternative PV array configurations that are predicted to produce no glare to the ATCT (unless otherwise noted). Azimuthal angle is measured clockwise from due north (0°) ; elevation angle is measured from 0° (facing up) to 90° (facing horizontal). Note: these analyses assumed an ATCT cabin elevation of 51.2 m. We were informed later that the cabin elevation was lower (~45 m), so other configurations with no glare to the ATCT are possible (e.g., Az=110 $^\circ$, El=20.6 $^\circ$).

Azimuthal Angle (degrees)	Elevation Angle (degrees)	Relative Annual Energy Production
180	43	100.0%*
200	20.6	93.9%**
120	40	88.9%
120	50	87.2%
110	30	85.0%
110	40	84.7%
120	60	83.7%
110	50	82.8%
130	70	81.5%
100	30	80.9%
100	20	80.8%
100	40	79.9%
110	60	79.3%
120	70	78.3%
100	50	77.6%
90	20	77.5%
210	80	76.9%
90	30	76.4%
220	80	75.8%
90	40	74.5%
110	70	74.2%
100	60	74.1%
130	80	74.0%
90	50	71.8%
120	80	71.3%
100	70	69.2%
90	60	68.1%
110	80	67.7%
90	70	63.4%
100	80	63.2%
90 *Maximum anaray mag	80	57.8%

^{*}Maximum energy production; produces glare to ATCT

Based on a review of the glare analyses, an alternative configuration of the PV modules was recommended where the assemblies are rotated 90° counter-clockwise so that they are facing

^{**}Current configuration; produces glare to ATCT





toward the east-southeast (110° from due north). The tilt of the modules remains the same (however, since the downward tilt of the roof is 1.2° from east to west, the actual tilt of the modules is 20.7° - 1.2° = 19.5° .

Figure 23 shows a screen image of the SGHAT analysis with the PV array outlined in blue and the location of the ATCT indicated by the red marker. The input parameters used in the model are shown in **Error! Reference source not found.**



Figure 23. Location of alternative PV array configuration (outlined in blue) rotated 90° counter-clockwise so that they are facing toward the east-southeast (110° from due north).

6.3 Flight path analysis

In addition to the ATCT, observation points along straight approaches to runways 35, 6, 17, 24 were also evaluated assuming a glide slope of 3 degrees. The distance legend on the Google map is used (along with a ruler) to specify observation points and desired distances from the touchdown point on the landing strip. See Table 2 and Figure 24 – Figure 27 for locations and elevations of observation points along the approach to these runways.

For this new configuration (PV assemblies rotated 90° counter-clockwise as shown in Figure 23), no glare was predicted to be observed in the ATCT or at the observation points along the approaches to runways 35, 6, and 17. It should be noted that the elevation of the ATCT observation point was varied between 40 - 51 m and no glare was predicted. Based on drawings of the ATCT tower, the elevation of the ATCT cabin is ~45 m.

The annual energy produced from this new configuration was predicted to be within ~1% of the existing configuration. The existing configuration consists of 2210 modules with a rated power





capacity of ~530 kW (~240 W/module). The new configuration has 247 additional modules for a rated power capacity of ~589 kW. Using these values, SGHAT predicts that the maximum annual energy production for the existing and new designs are 1.04 GWh and 1.16 GWh, respectively, assuming clear-sky conditions. Actual annual energy production will be less due to variable (lower) DNI when the sky is cloudy.

Table 2. Observation points for approaches to runways 35, 6, 17, and 24 assuming a 3 degree glide slope.

Observation	Height above	
Point	ground (ft)	
Threshold	52	
¼ mile	121	
½ mi.	190	
¾ mi.	259	
1 mi.	328	
1 ¼ mi.	397	
1 ½ mi.	467	
1 ¾ mi.	536	
2 mi.	605	



Figure 24. Observation points approaching Runway 35 from the southeast.







Figure 25. Observation points approaching Runway 6 from the southwest.

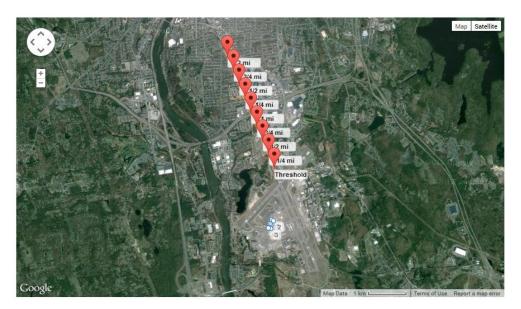


Figure 26. Observation points approaching Runway 17 from the northwest.



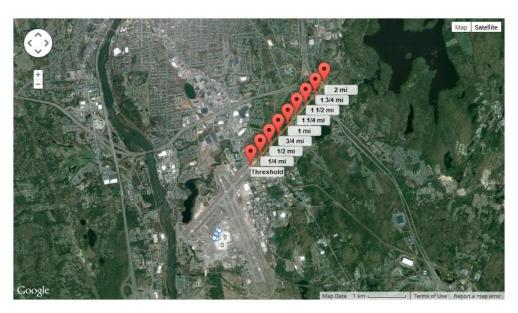


Figure 27. Observation points approaching Runway 24 from the northeast.





7. Appendix A - Analysis Parameters

- *Height Units*: Select the units of distance for the height of solar panels and the height above ground of each observation point in feet or meters.
- Subtended angle of the sun: The average subtended angle of the sun as viewed from earth is ~9.3 mrad or 0.5°.
- *Peak DNI*: The maximum Direct Normal Irradiance (W/m²) at the given location at solar noon. This value may be scaled at each time step to account for the changing position of the sun and reduced DNI in the mornings and evenings if the "variable" option is selected in the next field. On a clear sunny day at solar noon, a typical peak DNI is ~1,000 W/m².
- *DNI variability:* "Variable" scales the peak DNI at each time step based on the changing position of the sun. "Fixed" uses the peak DNI value for every time step throughout the analysis, with no scaling.
- *Ocular transmission coefficient:* The ocular transmission coefficient accounts for radiation that is absorbed in the eye before reaching the retina. A value of 0.5 is typical [1, 3].
- **Pupil diameter:** Diameter of the pupil (m). The size impacts the amount of light entering the eye and reaching the retina. Typical values range from 0.002 m for daylight-adjusted eyes to 0.008 m for nighttime vision [1, 3].
- *Eye focal length:* Distance between the nodal point (where rays intersect in the eye) and the retina. This value is used to determine the projected image size on the retina for a given subtended angle of the glare source. Typical value is 0.017 m [1, 3].
- *Time interval*: Specify the time step for the glare analysis. The sun position will be determined at each time step throughout the year. A time step of 1 minute yields excellent resolution.

8. Appendix B - PV Array Parameters

- *Orientation of array:* Specify the orientation of the array in degrees, measured clockwise from true north. Modules facing east would have an orientation of 90°, and modules facing south would have an orientation of 180°. The "Calculate declination" link can be used to determine the orientation if an angle based on magnetic north is known.
- *Tilt of solar panels:* Specify the tilt (elevation angle) of the modules in degrees, where 0° is facing up and 90° is facing horizontally.
- *Height of solar panels:* Specify height of modules above ground level in feet or meters.
- *Rated power*: Specify the rated power (kW) of the PV system. This is used to calculate the maximum annual energy produced (kWh) from the system in the prescribed configuration (assuming clear sunny days). This is useful for comparing alternative configurations to determine which one has the maximum energy production.





- *Reflectivity of PV module:* Specify the solar reflectance of the PV module. Although near-normal specular reflectance of PV glass (e.g., with antireflective coating) can be as low as ~1-2%, the reflectance can increase as the incidence angle of the sunlight increases (glancing angles). Based on evaluation of several different PV modules, an average reflectance of 10% is entered as a default value.
- *Slope error*: This parameter specifies the amount of scatter that occurs from the PV module. Mirror-like surfaces that produce specular reflections will have a slope error closer to zero, while rough surfaces that produce more scattered (diffuse) reflections have higher slope errors. Based on observed glare from different PV modules, an RMS slope error of ~10 mrad (which produces a total reflected beam spread of 0.13 rad or 7°) appears to be a reasonable value.

The following list comprises the array vertex parameters:

- *Latitude*: geographic coordinate, in degrees, representing north-south position of the point. 0 at the equator and positive above it.
- *Longitude*: geographic coordinate, in degrees, representing east-west position of the point. The value must be between -180 and 180, with 0 at the Prime Meridian and negative to the west of it.
- *Ground Elevation*: the height above sea level of the ground at the position of the point.
- *Height above ground*: The absolute height of the observation point above the ground elevation.
- *Total elevation*: the sum of the ground elevation and height above ground. Changes to this value are automatically reflected in the "height above ground" input. Use this if, for example, the PV array sits on a roof and the height of a building is known. Enter the height in the "total elevation" field and the heights above ground for each array vertex will be automatically determined.

9. Appendix C -Flight Path Parameters

- *direction*: angle, in degrees, from threshold along which to specify observations. 0 is true north, 90 is due east of true north. Note that the direction value may deviate from the specified runway angle.
- threshold height above ground: height of aircraft as it crosses threshold point.
- **glide slope**: angle, in degrees, of ascent/descent of aircraft along path.

For flight path observation point parameters, see Appendix D.





10. Appendix D - Observation Point Parameters

- *Latitude*: geographic coordinate, in degrees, representing north-south position of the point. 0 at the equator and positive above it.
- *Longitude*: geographic coordinate, in degrees, representing east-west position of the point. The value must be between -180 and 180, with 0 at the Prime Meridian and negative to the west of it.
- *Ground Elevation*: the height above sea level of the ground at the position of the point.
- *Height above ground*: The absolute height of the observation point above the ground elevation.

11. Acknowledgments

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12. References

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Additional references can be found at www.sandia.gov/glare.